

### PROBLEM DEFINITION & MOTIVATIONS

**Problem statement:** How can an attention mechanism select the most discriminative parts of the video?

**Joint is important for activity → high attention**

**Joint is wrongly located → low attention**

**Overview**

**Main challenges**

- High dimensional data
- Spatio-Temporal information
- Noise in the human pose

### MAIN IDEA

- Two modalities
  - ✓ 3D skeleton coordinates
  - ✓ RGB frames
- Two stream model

**Pose**

- Convolution features over space-time
- Long range dependencies are modeled with multiple layers of abstraction instead of a flat hidden RNN state

**RGB**

- Spatial attention mechanism over RGB hands crops
- Spatial attention adjusted at each timestep
- Conditioned on pose features
- Temporal Attention on LSTM features

### CONVNET ON SKELETON

**Topological ordering**

$X \in \mathbb{R}^{T \times J \times 3}$

**Preprocessing**

- The matrix  $X$  is filled with a **topological (neighborhood preserving) ordering**
- Position, Acceleration and Velocity

**Model**

- **Convolutions** extract spatio-temporal features
- $S$  : pose features (~body motion)

$T = \# \text{ timestep}$   
 $J = (\# \text{ subjects}) \times (\# \text{ joints after repeated topological ordering}) \times (\# \text{ coordinates dimension})$

### ATTENTION ON HANDS

**Spatial Attention around Hands crops**

- Inception features from RGB crops around hands
- **Attention weights** computed given
  - ✓ previous hidden state of RNN  $h_{t-1}$
  - ✓ pose features  $S$
- Fully differentiable

**Glossary:**

- $f_g$ : Inception feature vector
- $p_t$ : Spatial Attention weights for each hand
- $\tilde{v}_t$ : Output of the Spatial Attention framework - Input of the LSTM
- $f_h$ : LSTM
- $f_u$ : MLP
- $p'$ : Temporal Attention weights for each LSTM features
- $f_y$ : Classifier
- $u_{:,t}$ : LSTM features

**Temporal Attention on LSTM features**

### VISUALIZATION OF THE ATTENTION PROCESS

### EXPERIMENTAL RESULTS

**Comparison**

- State of the art on NTU RGB+D (NTU) (~57'000 videos - 60 classes)
- First to combine **3D skeleton data and RGB frames** on NTU
- Representations learned on NTU are transferable
  - ✓ **Transfer learning on smaller datasets**
  - ✓ State of the art on SBU Kinetics Interaction
  - ✓ Close to state of the art on MSR Daily Activity

**Ablation Study**

- Topological ordering matters for skeleton data
- Attention mechanism has a high impact on RGB only stream
  - ✓ Spatial Attention : + ~ 4 points
  - ✓ Spatio-Temporal Attention : + ~ 13 points
- Still a significant impact on the **two stream model**
  - ✓ Spatial Attention : + ~ 1.8 points
  - ✓ **Spatio-Temporal Attention** : + ~ 2.5 points

**Effect of joint ordering on NTU**

Methods	CS	CV	Avg
Random joint order	75.5	83.2	79.4
Topological order w/o double entries	76.2	83.9	80.0
Topological order	77.1	84.5	80.8

**NTU-RGB+D**

Methods	Pose	RGB	CS	CV	Avg
Lie Group	✓	-	50.1	52.8	51.5
Skeleton Quads	✓	-	38.6	41.4	40.0
Dynamic Skeletons	✓	-	60.2	65.2	62.7
HBRNN	✓	-	59.1	64.0	61.6
Deep LSTM	✓	-	60.7	67.3	64.0
Part-aware LSTM	✓	-	62.9	70.3	66.6
ST-LSTM + TrustG.	✓	-	69.2	77.7	73.5
STA-LSTM	✓	-	73.2	81.2	77.2
Ensemble LSTM	✓	-	74.6	81.3	78.0
GCA-LSTM	✓	-	74.4	82.8	78.6
JTM	✓	-	76.3	81.1	78.7
MTLN	✓	-	79.6	84.8	82.2
VA-LSTM	✓	-	79.4	87.6	83.5
View-invariant	✓	-	80.0	87.2	83.6
DSSCA-SSLM	✓	✓	74.9	-	-
STA-Hands	✓	✓	82.5	88.6	85.6
Hands Attention	✓	✓	84.8	90.6	87.7
C3D	-	✓	63.5	70.3	66.9
Resnet50+LSTM	-	✓	71.3	80.2	75.8
<b>Ours (pose only)</b>	✓	-	<b>77.1</b>	<b>84.5</b>	<b>80.8</b>
<b>Ours (RGB only)</b>	-	✓	<b>75.6</b>	<b>80.5</b>	<b>78.1</b>
<b>Ours (pose + RGB)</b>	✓	✓	<b>84.8</b>	<b>90.6</b>	<b>87.7</b>

**SBU Kinect Interaction**

Methods	Pose	RGB	Depth	Acc.
Raw skeleton	✓	-	-	79.4
Joint feature	✓	-	-	86.9
Co-occurrence RNN	✓	-	-	90.4
STA-LSTM	✓	-	-	91.5
ST-LSTM + TrustG.	✓	-	-	93.3
DSPM	✓	✓	✓	93.4
VA-LSTM	✓	-	✓	97.5
<b>Ours (pose only)</b>	✓	-	-	<b>90.5</b>
<b>Ours (RGB only)</b>	-	✓	✓	<b>72.0</b>
<b>Ours (pose + RGB)</b>	✓	✓	✓	<b>94.1</b>

**MSR Daily Interaction**

Methods	Pose	RGB	Depth	Acc.
Action Ensemble	✓	-	-	68.0
Efficient Pose-Based	✓	-	-	73.1
Moving Pose	✓	-	-	73.8
Moving Poselets	✓	-	-	74.5
MP	✓	-	-	79.9
Depth Fusion	-	-	✓	88.8
MMMP	✓	-	✓	91.3
DL-GSGC	✓	-	✓	95.0
DSSCA-SSLM	-	✓	✓	97.5
<b>Ours (pose only - no FT)</b>	✓	-	-	<b>72.2</b>
<b>Ours (pose only)</b>	✓	-	-	<b>74.6</b>
<b>Ours (RGB only)</b>	-	✓	✓	<b>75.3</b>
<b>Ours (pose + RGB)</b>	✓	✓	✓	<b>90.0</b>

**Ablation study on NTU**

Methods	Pose	RGB	Attention	CS	CV	Avg		
			Spatial	Temporal	Pose			
A	Pose only	✓	-	-	-	77.1	84.5	80.8
B	RGB only, no attention (sum of features)	-	✓	-	-	61.5	65.9	63.7
C	RGB only, no attention (concat of features)	-	✓	-	-	63.2	67.2	65.2
E	RGB only + spatial attention	o	✓	✓	-	67.4	71.2	69.3
G	RGB only + spatial-temporal attention	o	✓	✓	✓	75.6	80.5	78.1
H	Multi-modal, no attention (A+B)	✓	✓	-	-	83.0	88.5	85.3
I	Multi-modal, spatial attention (A+E)	✓	✓	✓	-	84.1	90.0	87.1
K	Multi-modal, spatial-temporal attention (A+E)	✓	✓	✓	✓	84.8	90.6	87.7